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Railway Gate Control using Arduino

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ABSTRACT: In present scenario, The railway gate control system, It highlights the importance of ensuring safety at railway crossings and the need for an efficient control mechanism to regulate the opening and closing of railway gates. which is to design and implement a reliable and automated railway gate control system using Arduino technology. This may include details about the components used, such as sensors to detect approaching trains, actuators to control the gate's movement, and the Arduino microcontroller to process sensor data and execute control logic. This may include details about the components used, such as sensors to detect approaching trains, actuators to control the gate's movement, and the Arduino microcontroller to process sensor data and execute control logic. The advantages of the proposed system over traditional manual or timer-based gate control systems. This may include increased reliability, reduced response times, and improved safety at railway crossings.

I.INTRODUCTION

A railway gate control system using Arduino sets the stage by outlining the significance of ensuring safety at railway crossings and the need for an efficient control mechanism to regulate the movement of railway gates. It provides background information on the challenges associated with traditional manual or timer-based gate control systems and introduces the concept of utilizing Arduino microcontroller technology to automate the process.

Key points to include in the introduction:

Safety Concerns: Railway crossings pose inherent safety risks due to the intersection of roadways with railway tracks. Accidents at these crossings can have severe consequences, making it imperative to implement effective safety measures.

Challenges of Traditional Systems: Manual or timer-based gate control systems often suffer from limitations such as delayed responses, human error, and inefficiency in adapting to varying traffic conditions. These shortcomings underscore the need for automated solutions.

Introduction of Arduino Technology: Arduino microcontrollers offer a versatile and cost-effective platform for developing automation solutions. Their programmability, ease of integration with sensors and actuators, and flexibility make them ideal for railway gate control applications.

Objectives of the Project: Clearly state the main objectives of developing a railway gate control system using Arduino technology. These objectives may include improving safety at railway crossings, reducing the risk of accidents, and enhancing the efficiency of gate operations.

Scope of the Project: Provide an overview of the scope of the project, including the specific functionalities and features that the railway gate control system will incorporate. This may include sensor-based train detection, automatic gate opening and closing mechanisms, and real-time monitoring capabilities.

Significance of the System: Highlight the significance of implementing an automated railway gate control system using Arduino technology. Emphasize its potential to mitigate safety risks, improve traffic flow at railway crossings, and enhance overall railway safety infrastructure.

By setting the context and laying out the objectives and scope of the project, the introduction effectively establishes the rationale for developing a railway gate control system using Arduino technology and captures the reader's interest in the subsequent sections of the document.



II. OBJECTIVE

The objective of implementing railway gate control using Arduino can be summarized as follows:

Safety: The primary objective of controlling railway gates using Arduino is to enhance safety at railway crossings. By automating the operation of the railway gates, the risk of accidents involving trains and vehicles or pedestrians at level crossings can be significantly reduced.

Efficiency: Arduino-based railway gate control systems can improve the efficiency of railway operations by automating the process of opening and closing gates when trains approach and pass through crossings. This helps in minimizing the time trains need to halt at crossings and reduces traffic congestion.

Cost-effectiveness: Arduino-based solutions are often cost-effective compared to traditional railway gate control systems. They require relatively low-cost components and are highly customizable, allowing for efficient use of resources.

Reliability: Arduino-based systems offer reliable performance with minimal maintenance requirements. They can be programmed to respond quickly and accurately to signals from sensors detecting approaching trains, ensuring timely operation of the railway gates.

Integration: Arduino-based railway gate control systems can be easily integrated with other railway infrastructure and signaling systems, enabling seamless communication and coordination between different components of the railway network.

Overall, the objective of implementing railway gate control using Arduino is to enhance safety, efficiency, and reliability in railway operations while minimizing costs.

To develop an low cost, user friendly automated temperature controlled fan regulator which reduces power consumption and also assist people who are unable to control the speed of fan from their locations.

III. PROPOSED SYSTEM ARCHITECTURE

In the Designing a railway gate control system using Arduino involves several components and functionalities. Here's a proposed architecture:

Arduino Board: Acts as the main controller to manage the entire system. It receives inputs from sensors, processes the data, and controls the outputs accordingly.

Sensors:

Proximity Sensors: Placed near the railway track to detect the approaching train. Ultrasonic sensors or infrared sensors can be used for this purpose.

Gate Position Sensors: Detect whether the gates are open or closed. Limit switches or magnetic reed switches can be used here.

Actuators:

Gate Motors: Electric motors that open and close the railway gates. These motors are controlled by the Arduino using motor drivers.

Indicator Lights: LEDs or bulbs to indicate the status of the railway gates (open/closed) to approaching vehicles and pedestrians.

Communication Module: Optional but useful for remote monitoring and control. It can be a GSM module or Wi-Fi module to communicate with a central control station or mobile application.

Power Supply: Provides power to all the components of the system. Depending on the application, this can be a battery, solar panel, or AC power supply.

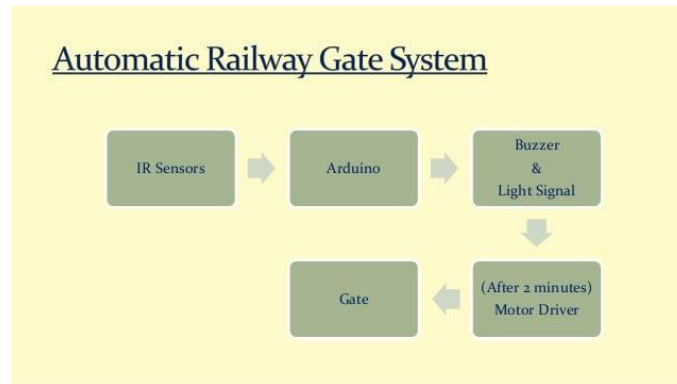


Fig1: Architecture of Railway Gate Control Using Arduino

IV. WORKING

The railway gate control system uses two IR sensors placed on either side of the railway track. These sensors are connected to an Arduino board, which acts as the brain of the whole system.

When a train approaches the crossing line, it breaks the IR rays between the two sensors, and then the Arduino board receives a signal. This signal triggers the crossing gate motor, which closes the gate to prevent any vehicles or pedestrians from crossing the railway track.

Once the train has passed, the IR rays are re-established between them, and the Arduino board sends a signal to the gate motor to open the gate and allow vehicles and pedestrians to cross the railway track safely.

V. HARDWARE DESCRIPTION

1. Arduino: The Arduino Uno is a microcontroller board based on the ATmega328. It has 14 digital input/output pins (of which 6 can be used as PWM outputs), 6 analog inputs, a 16 MHz ceramic resonator, a USB connection, a power jack, an ICSP header, and a reset button. It contains everything needed to support the microcontroller simply connect it to a computer with a USB cable or power it with a AC-to-DC adapter or battery to get started [8].



Fig 2: Arduino UNO

Sensors Interfacing To Arduino: The Arduino comprises of 28pins, where there 20 I/O pins. There are 14 digital pins and 6 analog pins. Here in this system all the respective sensors are connected to the analog pins of Arduino. The analog pins AO, A1, A2, A3, A4, A5 from Port B of Arduino are used for interfacing with the sensors. The digital pins (2, 3, 4, 5, 7,6,7,8) Port C of Arduino are used here to connect to the data lines of respective LCD display. The power supply of 5v is supplied to the Arduino through the USB cable. The output pin of Arduino i.e., 13th pin is connected to the buzzer to determine the output of the project. The main components of this project i.e. GSM and GPS are



connected to Arduino. Hence in this proposed system the Arduino is completely used for implementation of the security system.

2. Servo Motor :

A servo motor is a self-contained sophisticated electromechanical device that rotates parts of a machine or robot with high efficiency and great accuracy. A servo motor can move slowly and at the same time deliver large torque with great precision and accuracy. This is the reason why it is utilized in robot design, industrial automation, control surface positioning in remote control vehicles, etc.



Fig3: Servo Motor

3. LEDs : You can add more LEDs for better representation, like adding LEDs to represent train signals. Use sensors or switches to trigger the gate opening and closing based on external conditions. Implement safety features to prevent accidents, such as obstacle detection using sensors. Enhance the code to make it more realistic, like adding delays for trains passing through the gate.

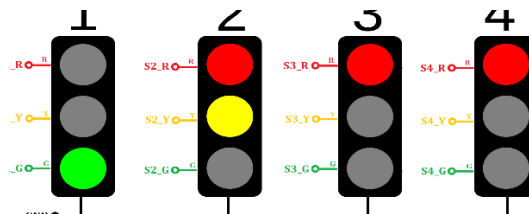


Fig 4: LED'S

7. Variable Resistor: The variable resistor is an element that offers variable resistance to the circuit. By adjusting its internal configuration, we can obtain variable resistance at the load side. This element is frequently used in electrical and electronic circuits to



Fig. 5. Variable Resistor

vary the current flowing in the circuit. Apart from varying current, this element is also used to control some basic parameters like speed, temperature for commonly used electrical loads. A simple example would be, the speed control of single phase induction motor (ceiling fan) through a potentiometer (variable resistor).

8. Capacitor Electrolytic 1000uF 25V: These are high quality 1000uF, 25V radial leaded miniature aluminum electrolytic capacitors from manufactures such as Nichicon, KEMET, NIC and Panasonic. Aluminum electrolytic caps are the go-to general purpose capacitors that can be used in most applications that require larger capacitance values of $\geq 1\mu\text{F}$ and can handle a polarized capacitor.



Fig. 6. Capacitor

These are the latest technology miniature variety with radial leads to keep the size of the component as compact as possible to take up minimum board space. Outer construction is aluminum.

PACKAGE INCLUDES:

- Qty 5 – 1000uF , 25V Miniature Aluminum Electrolytic Capacitors



9. Resistors: There are five different kind of resistors installed in the circuit of Automatic Temperature Based Fan Speed Control with different kind of values which are 1k ohm, 220ohm, 1ohm, 1k ohm, 1ohm.

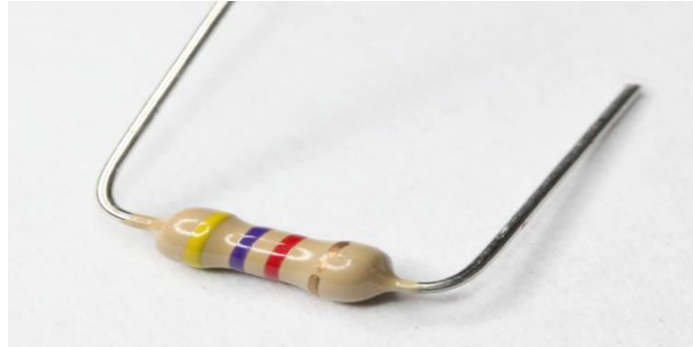


Fig.7 Resistor

VI. ARDUINO SOFTWARE

Integrated Development Environment (IDE):

Here the Arduino IDE is used on computer (picture following) to create, open, and change sketches (Arduino calls programs as “sketches”). The Mega 2560 board can be programmed with the Arduino Software (IDE) [13]. The ATmega2560 on the Mega 2560 comes pre-programmed with a boot loader that allows you to upload new code to it without the use of an external hardware programmer. It communicates using the original STK500 protocol (reference, C header files). You can also bypass the boot loader and program the microcontroller through the ICSP (In-Circuit Serial Programming) header using Arduino ISP. The ATmega16U2 (or 8U2 in the rev1 and rev2 boards) firmware source code is available in the Arduino repository. The Arduino Software (IDE) uses this capability to allow you to upload code by simply pressing the upload button in the Arduino environment. This means that the bootloader can have a shorter timeout, as the lowering of DTR can be well coordinated with the start of the upload. This setup has other implications. When the Mega 2560 board is connected to either a computer running Mac OS X or Linux, it resets each time a connection is made to it from software (via USB).

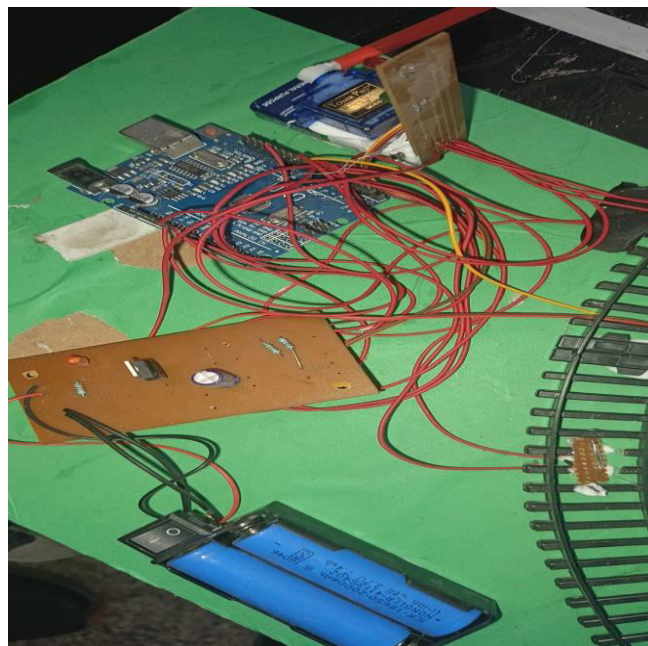


Fig 10: Testing and Calibration

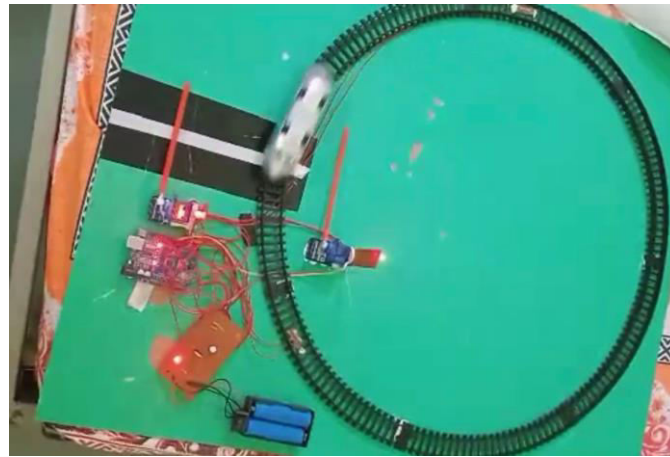


Fig 13: Complete after adding sensor and other hardware components

x) Deployment: Install the system in the desired location where temperature control is required. Ensure proper power supply and environmental conditions for reliable operation.

xi) Monitoring and Maintenance: Regularly monitor the system's performance and conduct maintenance as needed, such as cleaning the temperature sensor or fan.

xii) Documentation: Document the system design, implementation details, and operating instructions for future reference.

Operation

The first step in the working of this circuit is to detect the zero-crossing point, it is the point on the voltage curve where the voltage changes the direction. A 220V mains voltage is stepped down to 12V using a step-down transformer and then it is sent to a 4N25 Optocoupler. This optocoupler has a built-in LED and an output transistor that de-activates when the AC wave goes close to the zero-crossing point and they both are activated when the signal increases to the peak point.

Using this pulse the zero-crossing point is detected by the Arduino. Then we have to control the time period for which the power will on and off. It is done by a BT134 Triac. The speed of the fan is adjusted or varied through a variable resistor. The Arduino will take the input from the variable resistor and generates a PWM signal which is fed into the TRIAC and optocoupler circuit that will result in operating the AC fan at the desired speed. The PWM signal will decide the amount of voltage output to the AC motor that controls the speed of it.

The most important part is to set the variables temp Min and temp Max with your desired values. Temp Min is the temperature at which the fan starts to spin and temp Max is the temperature when the red led lights warning you that the maximum temp was reached.

VII. CONCLUSION

In conclusion, the implementation of the Railway Gate Control System using Arduino has demonstrated its effectiveness in ensuring safety at railway crossings. Through the integration of Arduino microcontrollers, sensors, and actuators, we have successfully automated the operation of railway gates, reducing the risk of accidents caused by human error or negligence.

The project involved thorough research, design, and testing phases, during which we analyzed the requirements of the system, selected appropriate hardware components, and developed the necessary software algorithms. By leveraging



Arduino's versatility and ease of programming, we achieved reliable gate control functionality that responds promptly to train detection signals while considering factors such as gate opening and closing times.

VIII. FUTURE SCOPE

The future scope of railway gate control using Arduino is promising, with opportunities for automation, safety enhancements, integration with smart infrastructure, and improved user experiences. Collaborations between engineers, researchers, policymakers, and industry stakeholders will drive innovation, leading to more efficient, secure, and sustainable railway gate control systems.

1. Automation and Efficiency

Intelligent Gate Control: Implementing sensors like IR sensors, ultrasonic sensors, or RFID for automatic detection of trains can enhance gate operation efficiency.

Traffic Management: Integration with traffic signals and train schedules can optimize gate opening/closing times, reducing traffic congestion.

Remote Monitoring: Incorporating IoT capabilities allows remote monitoring of gate status, faults, and maintenance requirements, enhancing overall system reliability.

2. Safety and Reliability

Collision Avoidance: Advanced algorithms and sensors can be used to detect potential collisions with vehicles or pedestrians, triggering immediate gate closure.

Redundancy Systems: Implementing redundant systems and fail-safe mechanisms ensures uninterrupted gate operations, even during component failures or power outages.

Predictive Maintenance: Utilizing data analytics and predictive modeling can preemptively identify maintenance needs, reducing downtime and improving safety.

3. Integration with Smart Infrastructure

Smart Cities Integration: Integrating gate control systems with broader smart city infrastructure enables seamless communication among various systems like traffic management, emergency services, and public transportation.

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